

12.3 The Dot Product

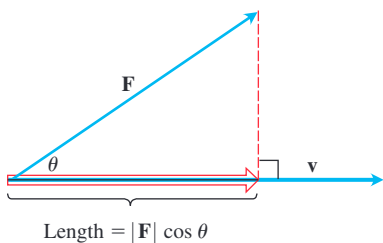


FIGURE 12.20 The magnitude of the force \mathbf{F} in the direction of vector \mathbf{v} is the length $|\mathbf{F}|\cos\theta$ of the projection of \mathbf{F} onto \mathbf{v} .

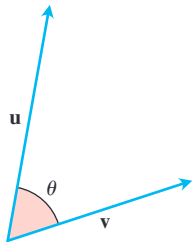


FIGURE 12.21 The angle between \mathbf{u} and \mathbf{v} given by Theorem 1 lies in the interval $[0, \pi]$.

If a force \mathbf{F} is applied to a particle moving along a path, we often need to know the magnitude of the force in the direction of motion. If \mathbf{v} is parallel to the tangent line to the path at the point where \mathbf{F} is applied, then we want the magnitude of \mathbf{F} in the direction of \mathbf{v} . Figure 12.20 shows that the scalar quantity we seek is the length $|\mathbf{F}|\cos\theta$, where θ is the angle between the two vectors \mathbf{F} and \mathbf{v} .

In this section we show how to calculate easily the angle between two vectors directly from their components. A key part of the calculation is an expression called the *dot product*. Dot products are also called *inner* or *scalar* products because the product results in a scalar, not a vector. After investigating the dot product, we apply it to finding the projection of one vector onto another (as displayed in Figure 12.20) and to finding the work done by a constant force acting through a displacement.

Angle Between Vectors

When two nonzero vectors \mathbf{u} and \mathbf{v} are placed so their initial points coincide, they form an angle θ of measure $0 \leq \theta \leq \pi$ (Figure 12.21). If the vectors do not lie along the same line, the angle θ is measured in the plane containing both of them. If they do lie along the same line, the angle between them is 0 if they point in the same direction and π if they point in opposite directions. The angle θ is the **angle between \mathbf{u} and \mathbf{v}** . Theorem 1 gives a formula to determine this angle.

THEOREM 1—Angle Between Two Vectors

The angle θ between two nonzero vectors $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$ and $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$ is given by

$$\theta = \arccos\left(\frac{u_1v_1 + u_2v_2 + u_3v_3}{|\mathbf{u}||\mathbf{v}|}\right).$$

We use the law of cosines to prove Theorem 1, but before doing so, we focus attention on the expression $u_1v_1 + u_2v_2 + u_3v_3$ in the calculation for θ . This expression is the sum of the products of the corresponding components of the vectors \mathbf{u} and \mathbf{v} .

DEFINITION The **dot product $\mathbf{u} \cdot \mathbf{v}$** (“**u dot v**”) of vectors $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$ and $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$ is the scalar

$$\mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2 + u_3v_3.$$

EXAMPLE 1 We illustrate the definition.

$$\begin{aligned} \text{(a)} \quad \langle 1, -2, -1 \rangle \cdot \langle -6, 2, -3 \rangle &= (1)(-6) + (-2)(2) + (-1)(-3) \\ &= -6 - 4 + 3 = -7 \end{aligned}$$

$$\text{(b)} \quad \left(\frac{1}{2}\mathbf{i} + 3\mathbf{j} + \mathbf{k}\right) \cdot (4\mathbf{i} - \mathbf{j} + 2\mathbf{k}) = \left(\frac{1}{2}\right)(4) + (3)(-1) + (1)(2) = 1 \quad \blacksquare$$

The dot product of a pair of two-dimensional vectors is defined in a similar fashion:

$$\langle u_1, u_2 \rangle \cdot \langle v_1, v_2 \rangle = u_1v_1 + u_2v_2.$$

We will see throughout the remainder of this text that the dot product is a key tool for many important geometric and physical calculations in space (and the plane).

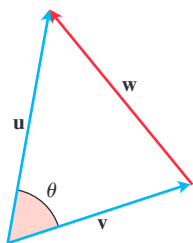


FIGURE 12.22 The parallelogram law of addition of vectors gives $\mathbf{w} = \mathbf{u} - \mathbf{v}$.

Proof of Theorem 1 Applying the law of cosines (Equation (8), Section 1.3) to the triangle in Figure 12.22, we find that

$$|\mathbf{w}|^2 = |\mathbf{u}|^2 + |\mathbf{v}|^2 - 2|\mathbf{u}||\mathbf{v}|\cos \theta \quad \text{Law of cosines}$$

$$2|\mathbf{u}||\mathbf{v}|\cos \theta = |\mathbf{u}|^2 + |\mathbf{v}|^2 - |\mathbf{w}|^2.$$

Because $\mathbf{w} = \mathbf{u} - \mathbf{v}$, the component form of \mathbf{w} is $\langle u_1 - v_1, u_2 - v_2, u_3 - v_3 \rangle$. So

$$|\mathbf{u}|^2 = (\sqrt{u_1^2 + u_2^2 + u_3^2})^2 = u_1^2 + u_2^2 + u_3^2$$

$$|\mathbf{v}|^2 = (\sqrt{v_1^2 + v_2^2 + v_3^2})^2 = v_1^2 + v_2^2 + v_3^2$$

$$\begin{aligned} |\mathbf{w}|^2 &= (\sqrt{(u_1 - v_1)^2 + (u_2 - v_2)^2 + (u_3 - v_3)^2})^2 \\ &= (u_1 - v_1)^2 + (u_2 - v_2)^2 + (u_3 - v_3)^2 \\ &= u_1^2 - 2u_1v_1 + v_1^2 + u_2^2 - 2u_2v_2 + v_2^2 + u_3^2 - 2u_3v_3 + v_3^2 \end{aligned}$$

and

$$|\mathbf{u}|^2 + |\mathbf{v}|^2 - |\mathbf{w}|^2 = 2(u_1v_1 + u_2v_2 + u_3v_3).$$

Therefore,

$$2|\mathbf{u}||\mathbf{v}|\cos \theta = |\mathbf{u}|^2 + |\mathbf{v}|^2 - |\mathbf{w}|^2 = 2(u_1v_1 + u_2v_2 + u_3v_3)$$

$$|\mathbf{u}||\mathbf{v}|\cos \theta = u_1v_1 + u_2v_2 + u_3v_3$$

$$\cos \theta = \frac{u_1v_1 + u_2v_2 + u_3v_3}{|\mathbf{u}||\mathbf{v}|}.$$

Thus, for $0 \leq \theta \leq \pi$, we have $\theta = \arccos\left(\frac{u_1v_1 + u_2v_2 + u_3v_3}{|\mathbf{u}||\mathbf{v}|}\right)$. ■

Dot Product and Angles

The angle between two nonzero vectors \mathbf{u} and \mathbf{v} is $\theta = \arccos\left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}||\mathbf{v}|}\right)$.

The dot product of two vectors \mathbf{u} and \mathbf{v} is given by $\mathbf{u} \cdot \mathbf{v} = |\mathbf{u}||\mathbf{v}|\cos \theta$.

EXAMPLE 2 Find the angle between $\mathbf{u} = \mathbf{i} - 2\mathbf{j} - 2\mathbf{k}$ and $\mathbf{v} = 6\mathbf{i} + 3\mathbf{j} + 2\mathbf{k}$.

Solution We use the formula above:

$$\mathbf{u} \cdot \mathbf{v} = (1)(6) + (-2)(3) + (-2)(2) = 6 - 6 - 4 = -4$$

$$|\mathbf{u}| = \sqrt{(1)^2 + (-2)^2 + (-2)^2} = \sqrt{9} = 3$$

$$|\mathbf{v}| = \sqrt{(6)^2 + (3)^2 + (2)^2} = \sqrt{49} = 7$$

$$\theta = \arccos\left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}||\mathbf{v}|}\right) = \arccos\left(\frac{-4}{(3)(7)}\right) \approx 1.76 \text{ radians or } 100.98^\circ. \quad \blacksquare$$

The angle formula applies to two-dimensional vectors as well. Note that the angle θ is acute if $\mathbf{u} \cdot \mathbf{v} > 0$ and obtuse if $\mathbf{u} \cdot \mathbf{v} < 0$.

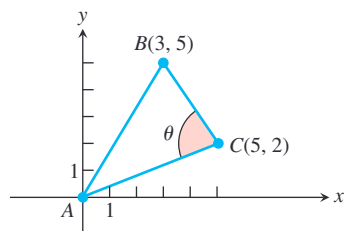


FIGURE 12.23 The triangle in Example 3.

EXAMPLE 3 Find the angle θ in the triangle ABC determined by the vertices $A = (0, 0)$, $B = (3, 5)$, and $C = (5, 2)$ (Figure 12.23).

Solution The angle θ is the angle between the vectors \overline{CA} and \overline{CB} . The component forms of these two vectors are

$$\overline{CA} = \langle -5, -2 \rangle \quad \text{and} \quad \overline{CB} = \langle -2, 3 \rangle.$$

First we calculate the dot product and magnitudes of these two vectors.

$$\begin{aligned}\overline{CA} \cdot \overline{CB} &= (-5)(-2) + (-2)(3) = 4 \\ |\overline{CA}| &= \sqrt{(-5)^2 + (-2)^2} = \sqrt{29} \\ |\overline{CB}| &= \sqrt{(-2)^2 + (3)^2} = \sqrt{13}\end{aligned}$$

Then, applying the angle formula, we have

$$\begin{aligned}\theta &= \arccos\left(\frac{\overline{CA} \cdot \overline{CB}}{|\overline{CA}||\overline{CB}|}\right) = \arccos\left(\frac{4}{(\sqrt{29})(\sqrt{13})}\right) \\ &\approx 78.1^\circ \text{ or } 1.36 \text{ radians.}\end{aligned}$$

Orthogonal Vectors

Two nonzero vectors \mathbf{u} and \mathbf{v} are perpendicular if the angle between them is $\pi/2$. For such vectors, we have $\mathbf{u} \cdot \mathbf{v} = 0$ because $\cos(\pi/2) = 0$. The converse is also true. If \mathbf{u} and \mathbf{v} are nonzero vectors with $\mathbf{u} \cdot \mathbf{v} = |\mathbf{u}||\mathbf{v}|\cos\theta = 0$, then $\cos\theta = 0$ and $\theta = \arccos 0 = \pi/2$. The following definition also allows for one or both of the vectors to be the zero vector.

DEFINITION Vectors \mathbf{u} and \mathbf{v} are orthogonal if $\mathbf{u} \cdot \mathbf{v} = 0$.

EXAMPLE 4 To determine if two vectors are orthogonal, calculate their dot product.

(a) $\mathbf{u} = \langle 3, -2 \rangle$ and $\mathbf{v} = \langle 4, 6 \rangle$ are orthogonal because $\mathbf{u} \cdot \mathbf{v} = (3)(4) + (-2)(6) = 0$.

(b) $\mathbf{u} = 3\mathbf{i} - 2\mathbf{j} + \mathbf{k}$ and $\mathbf{v} = 2\mathbf{j} + 4\mathbf{k}$ are orthogonal because

$$\mathbf{u} \cdot \mathbf{v} = (3)(0) + (-2)(2) + (1)(4) = 0.$$

(c) $\mathbf{0}$ is orthogonal to every vector \mathbf{u} because

$$\begin{aligned}\mathbf{0} \cdot \mathbf{u} &= \langle 0, 0, 0 \rangle \cdot \langle u_1, u_2, u_3 \rangle \\ &= (0)(u_1) + (0)(u_2) + (0)(u_3) = 0.\end{aligned}$$

Dot Product Properties and Vector Projections

The dot product obeys many of the laws that hold for ordinary products of real numbers (scalars).

Properties of the Dot Product

If \mathbf{u} , \mathbf{v} , and \mathbf{w} are any vectors and c is a scalar, then

- | | |
|---|---|
| 1. $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$ | 2. $(c\mathbf{u}) \cdot \mathbf{v} = \mathbf{u} \cdot (c\mathbf{v}) = c(\mathbf{u} \cdot \mathbf{v})$ |
| 3. $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$ | 4. $\mathbf{u} \cdot \mathbf{u} = \mathbf{u} ^2$ |
| 5. $\mathbf{0} \cdot \mathbf{u} = 0$. | |

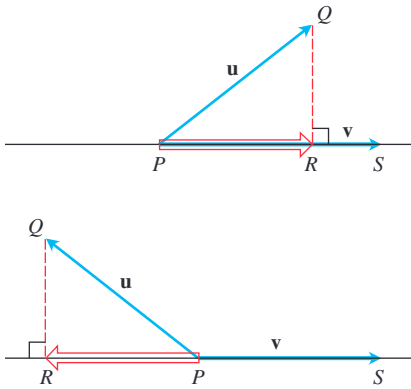


FIGURE 12.24 The vector projection of \mathbf{u} onto \mathbf{v} .

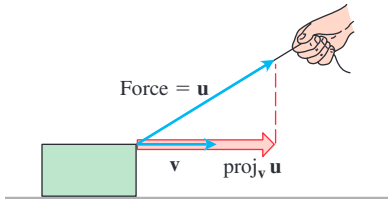


FIGURE 12.25 If we pull on the box with force \mathbf{u} , the effective force moving the box forward in the direction \mathbf{v} is the projection of \mathbf{u} onto \mathbf{v} .

Proofs of Properties 1 and 3 The properties are easy to prove using the definition. For instance, here are the proofs of Properties 1 and 3.

$$1. \mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2 + u_3v_3 = v_1u_1 + v_2u_2 + v_3u_3 = \mathbf{v} \cdot \mathbf{u}$$

$$\begin{aligned} 3. \mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) &= \langle u_1, u_2, u_3 \rangle \cdot \langle v_1 + w_1, v_2 + w_2, v_3 + w_3 \rangle \\ &= u_1(v_1 + w_1) + u_2(v_2 + w_2) + u_3(v_3 + w_3) \\ &= u_1v_1 + u_1w_1 + u_2v_2 + u_2w_2 + u_3v_3 + u_3w_3 \\ &= (u_1v_1 + u_2v_2 + u_3v_3) + (u_1w_1 + u_2w_2 + u_3w_3) \\ &= \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w} \end{aligned}$$

We now return to the problem of projecting one vector onto another, posed in the opening to this section. The **vector projection** of $\mathbf{u} = \overline{PQ}$ onto a nonzero vector $\mathbf{v} = \overline{PS}$ (Figure 12.24) is the vector \overline{PR} determined by dropping a perpendicular from Q to the line PS . The notation for this vector is

$$\text{proj}_{\mathbf{v}} \mathbf{u} \quad (\text{“the vector projection of } \mathbf{u} \text{ onto } \mathbf{v}\text{”}).$$

If \mathbf{u} represents a force, then $\text{proj}_{\mathbf{v}} \mathbf{u}$ represents the effective force in the direction of \mathbf{v} (Figure 12.25).

If the angle θ between \mathbf{u} and \mathbf{v} is acute, $\text{proj}_{\mathbf{v}} \mathbf{u}$ has length $|\mathbf{u}|\cos \theta$ and direction $\mathbf{v}/|\mathbf{v}|$ (Figure 12.26). If θ is obtuse, $\cos \theta < 0$ and $\text{proj}_{\mathbf{v}} \mathbf{u}$ has length $-|\mathbf{u}|\cos \theta$ and direction $-\mathbf{v}/|\mathbf{v}|$. In both cases,

$$\begin{aligned} \text{proj}_{\mathbf{v}} \mathbf{u} &= (|\mathbf{u}|\cos \theta) \frac{\mathbf{v}}{|\mathbf{v}|} \\ &= \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|} \right) \frac{\mathbf{v}}{|\mathbf{v}|} & |\mathbf{u}|\cos \theta &= \frac{|\mathbf{u}||\mathbf{v}|\cos \theta}{|\mathbf{v}|} = \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|} \\ &= \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \right) \mathbf{v}. \end{aligned}$$

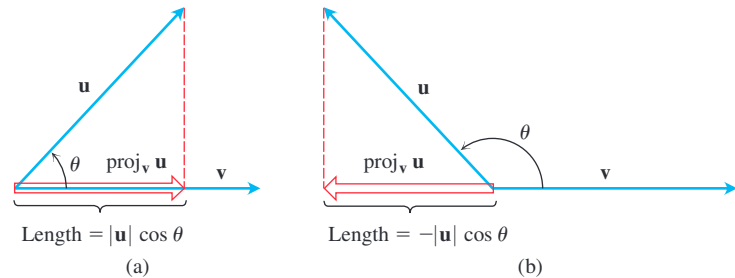


FIGURE 12.26 The length of $\text{proj}_{\mathbf{v}} \mathbf{u}$ is (a) $|\mathbf{u}|\cos \theta$ if $\cos \theta \geq 0$ and (b) $-|\mathbf{u}|\cos \theta$ if $\cos \theta < 0$.

The number $|\mathbf{u}|\cos \theta$ is called the **scalar component of \mathbf{u} in the direction of \mathbf{v}** . To summarize,

The vector projection of \mathbf{u} onto \mathbf{v} is the vector

$$\text{proj}_{\mathbf{v}} \mathbf{u} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \right) \mathbf{v} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|} \right) \frac{\mathbf{v}}{|\mathbf{v}|}. \quad (1)$$

The scalar component of \mathbf{u} in the direction of \mathbf{v} is the scalar

$$|\mathbf{u}|\cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|} = \mathbf{u} \cdot \frac{\mathbf{v}}{|\mathbf{v}|}. \quad (2)$$

Note that both the vector projection of \mathbf{u} onto \mathbf{v} and the scalar component of \mathbf{u} in the direction of \mathbf{v} depend only on the direction of the vector \mathbf{v} , not on its length. This is because in both cases we take the dot product of \mathbf{u} with the direction vector $\mathbf{v}/|\mathbf{v}|$, which is the direction of \mathbf{v} , and for the projection we go on to multiply the result by the direction vector.

EXAMPLE 5 Find the vector projection of $\mathbf{u} = 6\mathbf{i} + 3\mathbf{j} + 2\mathbf{k}$ onto $\mathbf{v} = \mathbf{i} - 2\mathbf{j} - 2\mathbf{k}$ and the scalar component of \mathbf{u} in the direction of \mathbf{v} .

Solution We find $\text{proj}_{\mathbf{v}} \mathbf{u}$ from Equation (1):

$$\begin{aligned}\text{proj}_{\mathbf{v}} \mathbf{u} &= \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \mathbf{v} = \frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{6 - 6 - 4}{1 + 4 + 4}(\mathbf{i} - 2\mathbf{j} - 2\mathbf{k}) \\ &= -\frac{4}{9}(\mathbf{i} - 2\mathbf{j} - 2\mathbf{k}) = -\frac{4}{9}\mathbf{i} + \frac{8}{9}\mathbf{j} + \frac{8}{9}\mathbf{k}.\end{aligned}$$

We find the scalar component of \mathbf{u} in the direction of \mathbf{v} from Equation (2):

$$\begin{aligned}|\mathbf{u}| \cos \theta &= \mathbf{u} \cdot \frac{\mathbf{v}}{|\mathbf{v}|} = (6\mathbf{i} + 3\mathbf{j} + 2\mathbf{k}) \cdot \left(\frac{1}{3}\mathbf{i} - \frac{2}{3}\mathbf{j} - \frac{2}{3}\mathbf{k}\right) \\ &= 2 - 2 - \frac{4}{3} = -\frac{4}{3}.\end{aligned}$$

Equations (1) and (2) also apply to two-dimensional vectors. We demonstrate this in the next example.

EXAMPLE 6 Find the vector projection of a force $\mathbf{F} = 5\mathbf{i} + 2\mathbf{j}$ onto $\mathbf{v} = \mathbf{i} - 3\mathbf{j}$ and the scalar component of \mathbf{F} in the direction of \mathbf{v} .

Solution The vector projection is

$$\begin{aligned}\text{proj}_{\mathbf{v}} \mathbf{F} &= \left(\frac{\mathbf{F} \cdot \mathbf{v}}{|\mathbf{v}|^2}\right) \mathbf{v} = \left(\frac{\mathbf{F} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}}\right) \mathbf{v} \\ &= \frac{5 - 6}{1 + 9}(\mathbf{i} - 3\mathbf{j}) = -\frac{1}{10}(\mathbf{i} - 3\mathbf{j}) \\ &= -\frac{1}{10}\mathbf{i} + \frac{3}{10}\mathbf{j}.\end{aligned}$$

The scalar component of \mathbf{F} in the direction of \mathbf{v} is

$$|\mathbf{F}| \cos \theta = \frac{\mathbf{F} \cdot \mathbf{v}}{|\mathbf{v}|} = \frac{5 - 6}{\sqrt{1 + 9}} = -\frac{1}{\sqrt{10}}.$$

EXAMPLE 7 Verify that the vector $\mathbf{u} - \text{proj}_{\mathbf{v}} \mathbf{u}$ is orthogonal to the projection vector $\text{proj}_{\mathbf{v}} \mathbf{u}$.

Solution The vector $\text{proj}_{\mathbf{v}} \mathbf{u} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2}\right) \mathbf{v}$ is parallel to \mathbf{v} . So it suffices to show that the vector $\mathbf{u} - \text{proj}_{\mathbf{v}} \mathbf{u}$ is orthogonal to \mathbf{v} . We verify orthogonality by showing that the dot product of $\mathbf{u} - \text{proj}_{\mathbf{v}} \mathbf{u}$ with \mathbf{v} is zero:

$$\begin{aligned}(\mathbf{u} - \text{proj}_{\mathbf{v}} \mathbf{u}) \cdot \mathbf{v} &= \mathbf{u} \cdot \mathbf{v} - \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \mathbf{v}\right) \cdot \mathbf{v} && \text{Definition of } \text{proj}_{\mathbf{v}} \mathbf{u} \\ &= \mathbf{u} \cdot \mathbf{v} - \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} (\mathbf{v} \cdot \mathbf{v}) && \text{Dot product property (2)} \\ &= \mathbf{u} \cdot \mathbf{v} - \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} |\mathbf{v}|^2 && \mathbf{v} \cdot \mathbf{v} = |\mathbf{v}|^2 \\ &= \mathbf{u} \cdot \mathbf{v} - \mathbf{u} \cdot \mathbf{v} = 0.\end{aligned}$$

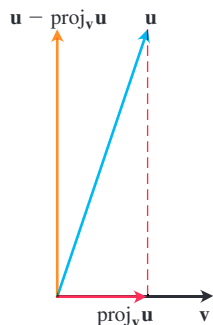


FIGURE 12.27 The vector \mathbf{u} is the sum of two perpendicular vectors: a vector $\text{proj}_v \mathbf{u}$, parallel to \mathbf{v} , and a vector $\mathbf{u} - \text{proj}_v \mathbf{u}$, perpendicular to \mathbf{v} .

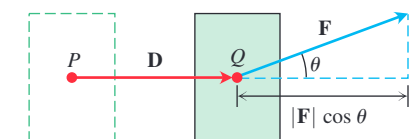


FIGURE 12.28 The work done by a constant force \mathbf{F} during a displacement \mathbf{D} is $(|\mathbf{F}| \cos \theta) |\mathbf{D}|$, which is the dot product $\mathbf{F} \cdot \mathbf{D}$.

Example 7 verifies that the vector $\mathbf{u} - \text{proj}_v \mathbf{u}$ is orthogonal to the projection vector $\text{proj}_v \mathbf{u}$ (which has the same direction as \mathbf{v}). So the equation

$$\mathbf{u} = \text{proj}_v \mathbf{u} + (\mathbf{u} - \text{proj}_v \mathbf{u}) = \underbrace{\left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \right) \mathbf{v}}_{\text{Parallel to } \mathbf{v}} + \underbrace{\left(\mathbf{u} - \left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \right) \mathbf{v} \right)}_{\text{Orthogonal to } \mathbf{v}}$$

expresses \mathbf{u} as a sum of orthogonal vectors (see Figure 12.27).

Work

In Chapter 6, we calculated the work done by a constant force of magnitude F in moving an object through a distance d as $W = Fd$. That formula holds only if the force is directed along the line of motion. If a force \mathbf{F} moving an object through a displacement $\mathbf{D} = \overline{PQ}$ has some other direction, the work is performed by the component of \mathbf{F} in the direction of \mathbf{D} . If θ is the angle between \mathbf{F} and \mathbf{D} (Figure 12.28), then

$$\begin{aligned} \text{Work} &= \left(\begin{array}{l} \text{scalar component of } \mathbf{F} \\ \text{in the direction of } \mathbf{D} \end{array} \right) (\text{length of } \mathbf{D}) \\ &= (|\mathbf{F}| \cos \theta) |\mathbf{D}| \\ &= \mathbf{F} \cdot \mathbf{D}. \end{aligned}$$

DEFINITION The work done by a constant force \mathbf{F} acting through a displacement $\mathbf{D} = \overline{PQ}$ is

$$W = \mathbf{F} \cdot \mathbf{D}.$$

EXAMPLE 8 If $|\mathbf{F}| = 40$ N (newtons), $|\mathbf{D}| = 3$ m, and $\theta = 60^\circ$, the work done by \mathbf{F} in acting from P to Q is

$$\begin{aligned} \text{Work} &= \mathbf{F} \cdot \mathbf{D} && \text{Definition} \\ &= |\mathbf{F}| |\mathbf{D}| \cos \theta \\ &= (40)(3) \cos 60^\circ && \text{Given values} \\ &= (120)(1/2) = 60 \text{ J (joules)}. \end{aligned}$$

We encounter more challenging work problems in Chapter 16 when we learn to find the work done by a variable force along a more general *path* in space.

The Dot Product of Two n -Dimensional Vectors

If $\mathbf{u} = \langle u_1, u_2, \dots, u_n \rangle$ and $\mathbf{v} = \langle v_1, v_2, \dots, v_n \rangle$ are n -dimensional vectors, then we define the dot product to be

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + \cdots + u_n v_n.$$

As for two- and three-dimensional vectors, the dot product is calculated by adding the products of the corresponding components of the two vectors.

This generalized dot product can be shown to satisfy the Properties of the Dot Product that were introduced earlier in this section, and similar terminology is used. If \mathbf{u} and \mathbf{v} are n -dimensional vectors, then

- \mathbf{u} and \mathbf{v} are said to be orthogonal if $\mathbf{u} \cdot \mathbf{v} = 0$,
- the vector projection of \mathbf{u} onto \mathbf{v} is $\text{proj}_v \mathbf{u} = \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{v}|^2} \mathbf{v}$, and

3. the angle between the vectors \mathbf{u} and \mathbf{v} is defined as $\theta = \arccos\left(\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}||\mathbf{v}|}\right)$. (The Cauchy-Schwarz inequality, $|\mathbf{u} \cdot \mathbf{v}| \leq |\mathbf{u}||\mathbf{v}|$, stated in Exercise 27 can be extended to n -dimensional vectors. This guarantees that $\frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}||\mathbf{v}|}$ is within the interval $[-1, 1]$.)

EXAMPLE 9 An automobile assembly plant makes four different car models. The components of the vector $\mathbf{u} = \langle 36, 50, 24, 10 \rangle$ indicate the plant's output of each model per hour, whereas the revenue per vehicle (in US dollars) of each model is represented by the vector $\mathbf{v} = \langle 24,000, 31,000, 39,000, 52,000 \rangle$. Calculate the dot product $\mathbf{u} \cdot \mathbf{v}$ and explain the significance of the value that was obtained.

Solution

$$\mathbf{u} \cdot \mathbf{v} = (36)(24,000) + (50)(31,000) + (24)(39,000) + (10)(52,000) = 3,870,000.$$

The value \$3,870,000 represents the total hourly revenue. ■

EXERCISES 12.3

For some exercises, a calculator may be helpful when expressing answers in decimal form.

Dot Product and Projections

In Exercises 1–8, find

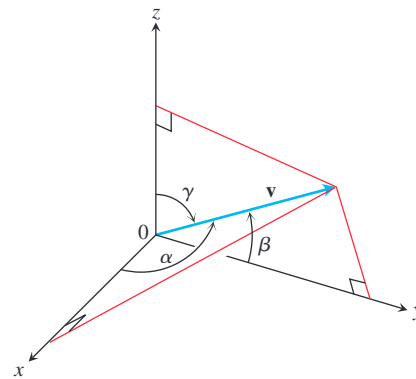
- $\mathbf{v} \cdot \mathbf{u}$, $|\mathbf{v}|$, $|\mathbf{u}|$
 - the cosine of the angle between \mathbf{v} and \mathbf{u}
 - the scalar component of \mathbf{u} in the direction of \mathbf{v}
 - the vector $\text{proj}_{\mathbf{v}} \mathbf{u}$.
- $\mathbf{v} = 2\mathbf{i} - 4\mathbf{j} + \sqrt{5}\mathbf{k}$, $\mathbf{u} = -2\mathbf{i} + 4\mathbf{j} - \sqrt{5}\mathbf{k}$
 - $\mathbf{v} = (3/5)\mathbf{i} + (4/5)\mathbf{k}$, $\mathbf{u} = 5\mathbf{i} + 12\mathbf{j}$
 - $\mathbf{v} = 10\mathbf{i} + 11\mathbf{j} - 2\mathbf{k}$, $\mathbf{u} = 3\mathbf{j} + 4\mathbf{k}$
 - $\mathbf{v} = 2\mathbf{i} + 10\mathbf{j} - 11\mathbf{k}$, $\mathbf{u} = 2\mathbf{i} + 2\mathbf{j} + \mathbf{k}$
 - $\mathbf{v} = 5\mathbf{j} - 3\mathbf{k}$, $\mathbf{u} = \mathbf{i} + \mathbf{j} + \mathbf{k}$
 - $\mathbf{v} = -\mathbf{i} + \mathbf{j}$, $\mathbf{u} = \sqrt{2}\mathbf{i} + \sqrt{3}\mathbf{j} + 2\mathbf{k}$
 - $\mathbf{v} = 5\mathbf{i} + \mathbf{j}$, $\mathbf{u} = 2\mathbf{i} + \sqrt{17}\mathbf{j}$
 - $\mathbf{v} = \left\langle \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{3}} \right\rangle$, $\mathbf{u} = \left\langle \frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{3}} \right\rangle$

Angle Between Vectors

Find the angles between the vectors in Exercises 9–12 to the nearest hundredth of a radian.

- $\mathbf{u} = 2\mathbf{i} + \mathbf{j}$, $\mathbf{v} = \mathbf{i} + 2\mathbf{j} - \mathbf{k}$
 - $\mathbf{u} = 2\mathbf{i} - 2\mathbf{j} + \mathbf{k}$, $\mathbf{v} = 3\mathbf{i} + 4\mathbf{k}$
 - $\mathbf{u} = \sqrt{3}\mathbf{i} - 7\mathbf{j}$, $\mathbf{v} = \sqrt{3}\mathbf{i} + \mathbf{j} - 2\mathbf{k}$
 - $\mathbf{u} = \mathbf{i} + \sqrt{2}\mathbf{j} - \sqrt{2}\mathbf{k}$, $\mathbf{v} = -\mathbf{i} + \mathbf{j} + \mathbf{k}$
13. **Triangle** Find the measures of the angles of the triangle whose vertices are $A = (-1, 0)$, $B = (2, 1)$, and $C = (1, -2)$.
14. **Rectangle** Find the measures of the angles between the diagonals of the rectangle whose vertices are $A = (1, 0)$, $B = (0, 3)$, $C = (3, 4)$, and $D = (4, 1)$.

15. **Direction angles and direction cosines** The *direction angles* α , β , and γ of a vector $\mathbf{v} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ are defined as follows:
- α is the angle between \mathbf{v} and the positive x -axis ($0 \leq \alpha \leq \pi$).
 - β is the angle between \mathbf{v} and the positive y -axis ($0 \leq \beta \leq \pi$).
 - γ is the angle between \mathbf{v} and the positive z -axis ($0 \leq \gamma \leq \pi$).



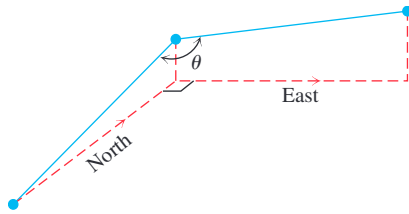
- a. Show that

$$\cos \alpha = \frac{a}{|\mathbf{v}|}, \quad \cos \beta = \frac{b}{|\mathbf{v}|}, \quad \cos \gamma = \frac{c}{|\mathbf{v}|},$$

and $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = 1$. These cosines are called the *direction cosines* of \mathbf{v} .

- b. **Unit vectors are built from direction cosines** Show that if $\mathbf{v} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ is a unit vector, then a , b , and c are the direction cosines of \mathbf{v} .
16. **Water main construction** A water main is to be constructed with a 20% grade in the north direction and a 10% grade in the

east direction. Determine the angle θ required in the water main for the turn from north to east.



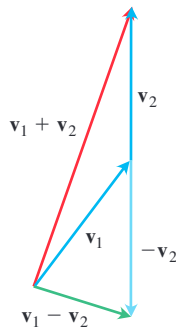
For Exercises 17 and 18, find the acute angle between the given lines by using vectors parallel to the lines.

17. $y = x$, $y = 2x + 3$

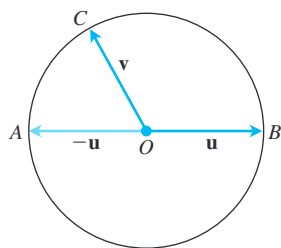
18. $2 - x + 2y = 0$, $3x - 4y = -12$

Theory and Examples

19. **Sums and differences** In the accompanying figure, it looks as if $\mathbf{v}_1 + \mathbf{v}_2$ and $\mathbf{v}_1 - \mathbf{v}_2$ are orthogonal. Is this mere coincidence, or are there circumstances under which we may expect the sum of two vectors to be orthogonal to their difference? Give reasons for your answer.



20. **Orthogonality on a circle** Suppose that AB is the diameter of a circle with center O and that C is a point on one of the two arcs joining A and B . Show that \overline{CA} and \overline{CB} are orthogonal.

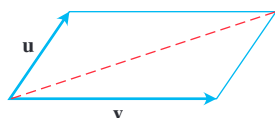


21. **Diagonals of a rhombus** Show that the diagonals of a rhombus (parallelogram with sides of equal length) are perpendicular.

22. **Perpendicular diagonals** Show that squares are the only rectangles with perpendicular diagonals.

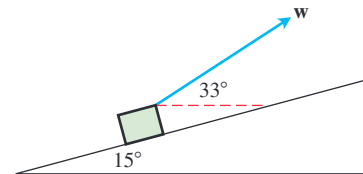
23. **When parallelograms are rectangles** Prove that a parallelogram is a rectangle if and only if its diagonals are equal in length. (This fact is often exploited by carpenters.)

24. **Diagonal of parallelogram** Show that the indicated diagonal of the parallelogram determined by vectors \mathbf{u} and \mathbf{v} bisects the angle between \mathbf{u} and \mathbf{v} if $|\mathbf{u}| = |\mathbf{v}|$.



25. **Projectile motion** A gun with muzzle velocity of 1200 ft/sec is fired at an angle of 8° above the horizontal. Find the horizontal and vertical components of the velocity.

26. **Inclined plane** Suppose that a box is being towed up an inclined plane as shown in the figure. Find the force \mathbf{w} needed to make the component of the force parallel to the inclined plane equal to 2.5 lb.



27. **a. Cauchy-Schwarz inequality** Since $\mathbf{u} \cdot \mathbf{v} = |\mathbf{u}||\mathbf{v}|\cos\theta$, show that the inequality $|\mathbf{u} \cdot \mathbf{v}| \leq |\mathbf{u}||\mathbf{v}|$ holds for any vectors \mathbf{u} and \mathbf{v} .

b. Under what circumstances, if any, does $|\mathbf{u} \cdot \mathbf{v}|$ equal $|\mathbf{u}||\mathbf{v}|$? Give reasons for your answer.

28. **Dot multiplication is positive definite** Show that dot multiplication of vectors is *positive definite*; that is, show that $\mathbf{u} \cdot \mathbf{u} \geq 0$ for every vector \mathbf{u} and that $\mathbf{u} \cdot \mathbf{u} = 0$ if and only if $\mathbf{u} = \mathbf{0}$.

29. **Orthogonal unit vectors** If \mathbf{u}_1 and \mathbf{u}_2 are orthogonal unit vectors and $\mathbf{v} = a\mathbf{u}_1 + b\mathbf{u}_2$, find $\mathbf{v} \cdot \mathbf{u}_1$.

30. **Cancellation in dot products** In real-number multiplication, if $uv_1 = uv_2$ and $u \neq 0$, we can cancel the u and conclude that $v_1 = v_2$. Does the same rule hold for the dot product? That is, if $\mathbf{u} \cdot \mathbf{v}_1 = \mathbf{u} \cdot \mathbf{v}_2$ and $\mathbf{u} \neq \mathbf{0}$, can you conclude that $\mathbf{v}_1 = \mathbf{v}_2$? Give reasons for your answer.

31. If \mathbf{u} and \mathbf{v} are orthogonal, show that $\text{proj}_{\mathbf{v}} \mathbf{u} = \mathbf{0}$.

32. A force $\mathbf{F} = 2\mathbf{i} + \mathbf{j} - 3\mathbf{k}$ is applied to a spacecraft with velocity vector $\mathbf{v} = 3\mathbf{i} - \mathbf{j}$. Express \mathbf{F} as a sum of a vector parallel to \mathbf{v} and a vector orthogonal to \mathbf{v} .

Equations for Lines in the Plane

33. **Line perpendicular to a vector** Show that $\mathbf{v} = a\mathbf{i} + b\mathbf{j}$ is perpendicular to the line $ax + by = c$. (*Hint:* For a and b nonzero, establish that the slope of the vector \mathbf{v} is the negative reciprocal of the slope of the given line. Also verify the statement when $a = 0$ or $b = 0$.)

34. **Line parallel to a vector** Show that the vector $\mathbf{v} = a\mathbf{i} + b\mathbf{j}$ is parallel to the line $bx - ay = c$. (*Hint:* For a and b nonzero, establish that the slope of the line segment representing \mathbf{v} is the same as the slope of the given line. Also verify the statement when $a = 0$ or $b = 0$.)

In Exercises 35–38, use the result of Exercise 33 to find an equation for the line through P perpendicular to \mathbf{v} . Then sketch the line. Include \mathbf{v} in your sketch as a vector starting at the origin.

35. $P(2, 1)$, $\mathbf{v} = \mathbf{i} + 2\mathbf{j}$ 36. $P(-1, 2)$, $\mathbf{v} = -2\mathbf{i} - \mathbf{j}$

37. $P(-2, -7)$, $\mathbf{v} = -2\mathbf{i} + \mathbf{j}$ 38. $P(11, 10)$, $\mathbf{v} = 2\mathbf{i} - 3\mathbf{j}$

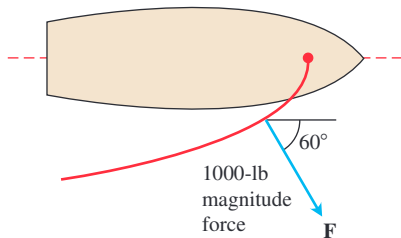
In Exercises 39–42, use the result of Exercise 34 to find an equation for the line through P parallel to \mathbf{v} . Then sketch the line. Include \mathbf{v} in your sketch as a vector starting at the origin.

39. $P(-2, 1)$, $\mathbf{v} = \mathbf{i} - \mathbf{j}$ 40. $P(0, -2)$, $\mathbf{v} = 2\mathbf{i} + 3\mathbf{j}$

41. $P(1, 2)$, $\mathbf{v} = -\mathbf{i} - 2\mathbf{j}$ 42. $P(1, 3)$, $\mathbf{v} = 3\mathbf{i} - 2\mathbf{j}$

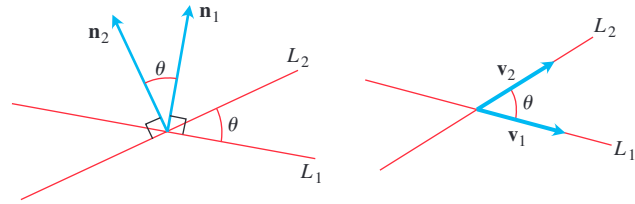
Work

- 43. Work along a line** Find the work done by a force $\mathbf{F} = 5\mathbf{i}$ (magnitude 5 N) in moving an object along the line from the origin to the point (1, 1) (distance in meters).
- 44. Locomotive** The Union Pacific's *Big Boy* locomotive could pull 6000-ton trains with a tractive effort (pull) of 602,148 N (135,375 lb). At this level of effort, about how much work did *Big Boy* do on the (approximately straight) 605-km journey from San Francisco to Los Angeles?
- 45. Inclined plane** How much work does it take to slide a crate 20 m along a loading dock by pulling on it with a 200-N force at an angle of 30° from the horizontal?
- 46. Sailboat** The wind passing over a boat's sail exerted a 1000-lb magnitude force \mathbf{F} as shown here. How much work did the wind perform in moving the boat forward 1 mi? Answer in foot-pounds.



Angles Between Lines in the Plane

The acute angle between intersecting lines that do not cross at right angles is the same as the angle determined by vectors normal to the lines or by vectors parallel to the lines.



Use this fact and the results of Exercise 33 or 34 to find the acute angles between the lines in Exercises 47–52.

- 47.** $3x + y = 5, \quad 2x - y = 4$
48. $y = \sqrt{3}x - 1, \quad y = -\sqrt{3}x + 2$
49. $\sqrt{3}x - y = -2, \quad x - \sqrt{3}y = 1$
50. $x + \sqrt{3}y = 1, \quad (1 - \sqrt{3})x + (1 + \sqrt{3})y = 8$
51. $3x - 4y = 3, \quad x - y = 7$
52. $12x + 5y = 1, \quad 2x - 2y = 3$

Dot Products of n -Dimensional Vectors

In Exercises 53–56, (a) find $\mathbf{u} \cdot \mathbf{v}$ and (b) determine whether the vectors \mathbf{u} and \mathbf{v} are orthogonal.

- 53.** $\mathbf{u} = \langle 3, 2, -4, 0 \rangle, \quad \mathbf{v} = \langle 1, 0, 0, 2 \rangle$
54. $\mathbf{u} = \langle -2, 1, 1, 2 \rangle, \quad \mathbf{v} = \langle -1, 2, -2, -1 \rangle$
55. $\mathbf{u} = \langle 6, 3, 0, 1, -2 \rangle, \quad \mathbf{v} = \langle 0, 2, -7, 0, 3 \rangle$
56. $\mathbf{u} = \langle 4, 2, -3, -2, 1, 5 \rangle, \quad \mathbf{v} = \langle 3, -3, 2, -2, 1, -1 \rangle$

12.4 The Cross Product

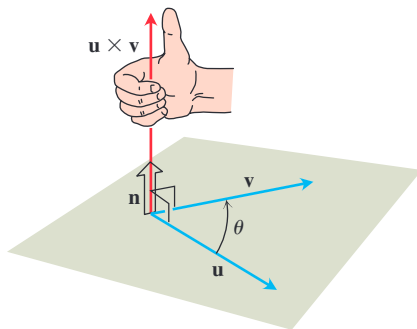


FIGURE 12.29 The construction of $\mathbf{u} \times \mathbf{v}$.

In studying lines in the plane, when we needed to describe how a line was tilting, we used the notions of slope and angle of inclination. In space, we want a way to describe how a plane is tilting. We accomplish this by multiplying two vectors in the plane together to get a third vector perpendicular to the plane. The direction of this third vector tells us the “inclination” of the plane. The product we use to multiply the vectors together is the *vector* or *cross product*, the second of the two vector multiplication methods. The cross product gives us a simple way to find a variety of geometric quantities, including volumes, areas, and perpendicular vectors. We study the cross product in this section.

The Cross Product of Two Vectors in Space

We start with two nonzero vectors \mathbf{u} and \mathbf{v} in space. Two vectors are *parallel* if one is a nonzero multiple of the other. If \mathbf{u} and \mathbf{v} are not parallel, they determine a plane. The vectors in this plane are linear combinations of \mathbf{u} and \mathbf{v} , so they can be written as a sum $a\mathbf{u} + b\mathbf{v}$. We select the unit vector \mathbf{n} perpendicular to the plane by the **right-hand rule**. This means that we choose \mathbf{n} to be the unit normal vector that points the way your right thumb points when your fingers curl through the angle θ from \mathbf{u} to \mathbf{v} (Figure 12.29). Then we define a new vector as follows.

DEFINITION The cross product $\mathbf{u} \times \mathbf{v}$ (“ \mathbf{u} cross \mathbf{v} ”) is the vector

$$\mathbf{u} \times \mathbf{v} = (|\mathbf{u}||\mathbf{v}| \sin \theta) \mathbf{n}.$$